

Nonlinear Dynamics and Complex Systems

Exercise No. 1

Population Dynamics

1) A Predator-Prey-Model (Rabbits vs. Foxes)

Two species of animals with population numbers N_1 and N_2 coexist in a common habitat. The predators (N_2 , “foxes”) feed by eating the prey (N_1 , “rabbits”). The prey feeds on plants and is assumed to multiply unboundedly if left alone. A simple ansatz for the evolution of the populations (continuous in time) is given by

$$\frac{dN_1}{dt} = N_1(a - bN_2), \quad (1)$$

$$\frac{dN_2}{dt} = N_2(cN_1 - d) \quad (2)$$

with positive constants a, b, c, d .

- Interpret these equations and the meaning of the constants.
- By rescaling the constants and the time coordinate show that (1), (2) can be transformed into the dimensionless form (the *Lotka-Volterra equation*)

$$\frac{dx}{d\tau} = x(1 - y), \quad (3)$$

$$\frac{dy}{d\tau} = \alpha y(x - 1). \quad (4)$$

- Investigate the fixed points of (3), (4) and their stability.
- By integrating dy/dx resulting from (3), (4) show that the phase space trajectories satisfy the equation

$$\alpha x + y - \ln(x^\alpha y) = C$$

where C is a conserved quantity ($C \geq 1 + \alpha$).

- Using MAPLE: Draw typical trajectories $x(t)$, $y(t)$ and phase space plots. Interpret the results

2) A Competition Model (Rabbits vs. Sheep)

Two species of animals (N_1 , “rabbits” and N_2 , “sheep”) live in the same habitat and compete for the same limited food source. An ansatz for the time evolution of the populations

is given by

$$\frac{dN_1}{dt} = r_1 N_1 \left(1 - \frac{N_1}{K_1} - b_1 N_2 \right), \quad (5)$$

$$\frac{dN_2}{dt} = r_2 N_2 \left(1 - \frac{N_2}{K_2} - b_2 N_1 \right) \quad (6)$$

with positive constants $r_1, r_2, K_1, K_2, b_1, b_2$.

a) Interpret these equations and the meaning of the constants.

b) By rescaling the constants and the time show that (5), (6) can be transformed into the dimensionless form

$$\frac{dx}{d\tau} = x(1 - x - ay) \equiv f(x, y), \quad (7)$$

$$\frac{dy}{d\tau} = \rho y(1 - y - bx) \equiv g(x, y). \quad (8)$$

c) By investigating the “nullclines” (i.e., the curves with $f(x, y) = 0$ or $g(x, y) = 0$) find the fixed points of the system.

d) As an example, study the case $a = \frac{4}{3}, b = \frac{3}{2}, \rho = \frac{2}{3}$. Investigate the stability of the fixed points and draw a phase space diagram. Can the two species coexist peacefully? Could this outcome change for other values of the parameters?