Plasma Astrophysics Chapter 3: Kinetic Theory

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Kinetic Theory

- Single particle description: tenuous plasma with strong external fields, important for gaining insight into physical processes involved
- For a system with a large number of particles it is neither possible nor desirable to determine the motion of every single particle

=> statistical approaches, average macroscopic properties

• Kinetic theory averages out microscopic information to obtain statistical, kinetic equations. No knowledge of individual particle motion is required to describe observable phenomena.

Particle Phase Space

• A particle's dynamical state can be specified using its position and velocity:

 $\boldsymbol{r} = (x, y, z)$ and $\boldsymbol{v} = (v_x, v_y, v_z)$

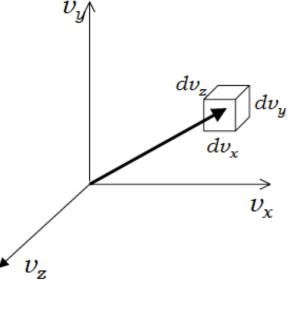
• Combining position and velocity information gives particle's position in phase space:

$$(\boldsymbol{r}, \boldsymbol{v}) = (x, y, z, v_x, v_y, v_z)$$

- The state space for position and momentum (or velocity) is a 6D phase space
- Volume of a small element of velocity space is

$$dv_x dv_y dv_z = d^3 v = d\boldsymbol{v}$$

• Volume element in phase space is d^3rd^3v



Velocity distribution functions

- Single-particle approach has limited application where collective motion not important. Non-zero electric fields in a plasma generally arise self-consistently, so must consider collective motion of many plasma particles.
- State of plasma described by the *velocity distribution function* : $f(x, y, z, v_x, v_y, v_z, t)$
- Gives the number of particles per unit volume as a position r and a time t with velocity, v_x , v_y , v_z . Has 7 independent variables defining a 6D phase space.
- Number of particles in a phase space volume d^3rd^3v is: $dn = f(r, w, t) dr dw dv dw dw = f(r, w, t) d^3rd^3$

 $dn = f(r, v, t) dx dy dz dv_x dv_y dv_z = f(r, v, t) d^3 r d^3 v$

• The total number of particles is therefore

$$n = \int_{-\infty}^{\infty} f(r, v, t) d^3r d^3v$$

Moments

• Let *f*(*x*) be any function that is defined and positive on an interval [*a*, *b*]. The moments of this function is defined as

Zeroth moment
$$M_0 = \int_b^a f(x) dx$$

First moment $M_1 = \int_b^a x f(x) dx$
Second moment $M_2 = \int_b^a x^2 f(x) dx$

nth moment
$$M_n = \int_b^a x^n f(x) dx$$

Moments (cont.)

• In particular case that distribution is a probability density, p(x), then

$$M_0 = 1$$

$$M_1 = \int_b^a x p(x) dx = \langle x \rangle = \text{mean}(x)$$

$$M_2 = \int_b^a x^2 p(x) dx = \text{variance}(x)$$

- Higher order moments correspond to skewness and kurtosis.
- Skewness: a measure of symmetry or lack of symmetry
- Kurtosis: a measure of whether the data are peaked or flat relative to normal distribution

Moments of distribution function

- Velocity distribution function gives microscopic description of statistical information on particles. However, most important use is in determining macroscopic (i.e., averages) values such as density, current, etc.
- Zeroth order moment of $f(\mathbf{r}, \mathbf{v}, t)$ is: $n(\mathbf{r}, t) = \int_{-\infty}^{\infty} f(\mathbf{r}, \mathbf{v}, t) d^3 v$
- *First order moment* is bulk velocity: $\boldsymbol{u} = \frac{1}{n} \int_{-\infty}^{\infty} \boldsymbol{v} f(\boldsymbol{r}, \boldsymbol{v}, t) d^3 v$
- Charge and current densities of spices (s) can be expressed in using moments: $a_0 = \sum a_0 n_0$, $i = \sum a_0 n_0$, u

$$\rho_e = \sum_s q_s n_s \quad \boldsymbol{j} = \sum_s q_s n_s \boldsymbol{u}_s$$

• Second order moment relates to kinetic energy

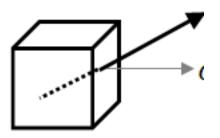
$$\left\langle \frac{1}{2}mv^2 \right\rangle = \frac{1}{n} \int_{-\infty}^{\infty} \frac{1}{2}mv^2 f(\boldsymbol{r}, \boldsymbol{v}, t) d^3v$$

Derivation of Boltzmann Equation

- Evolution of f(r,v,t) is described by the *Boltzmann Equation*.
- Consider particles entering and leaving a small volume of space. Since *r* and *v* is independent, can treat separately.
- Position: Number of particles leaving d^3r per second through its surface $d\mathbf{S}$ is

$$\int f(\boldsymbol{r}, \boldsymbol{v}, t) \dot{\boldsymbol{r}} \cdot d\boldsymbol{S} = \int f(\boldsymbol{r}, \boldsymbol{v}, t) \boldsymbol{v} \cdot d\boldsymbol{S}$$

• Velocity: Number of particles leaving d^3v per second through its surface $d\mathbf{S}_v$ is



$$\int f(\boldsymbol{r}, \boldsymbol{v}, t) \dot{\boldsymbol{v}} \cdot d\boldsymbol{S}_v = \int f(\boldsymbol{r}, \boldsymbol{v}, t) \boldsymbol{a} \cdot d\boldsymbol{S}_v$$

• So the net number of particles leaving the phase space volume d^3rd^3v is $\int f(\mathbf{r}, \mathbf{v}, t)\mathbf{v} \cdot d\mathbf{S}d^3v + \int f(\mathbf{r}, \mathbf{v}, t)\mathbf{a} \cdot d\mathbf{S}_v d^3r$

Derivation of Boltzmann Equation (cont.)

• The rate of change of particle number in d^3rd^3v is:

$$\frac{\partial}{\partial t} \left[\int f d^3 r d^3 v \right] = - \left[\int f \boldsymbol{v} \cdot d\boldsymbol{S} d^3 v + \int f \boldsymbol{a} \cdot d\boldsymbol{S}_v d^3 r \right]$$

• As total number of particles in d^3rd^3v is conserved: $\partial \left[\int f d^3r d^3v \right] + \left[\int f a \cdot dS d^3v + \int f a \cdot dS d^3r \right]$

$$\frac{\partial}{\partial t} \left[\int f d^3 r d^3 v \right] + \left[\int f \boldsymbol{v} \cdot d\boldsymbol{S} d^3 v + \int f \boldsymbol{a} \cdot d\boldsymbol{S}_v d^3 r \right] = 0$$

• Recall Gauss' Divergence Theorem:

$$\int_{V} (\nabla \cdot \boldsymbol{F}) dV = \int_{S} (\boldsymbol{F} \cdot \boldsymbol{n}) dS$$

• Can change integral over dS to d^3r :

$$\frac{\partial}{\partial t} \left[\int f d^3 r d^3 v \right] + \left[\int \nabla_r \cdot (f \boldsymbol{v}) d^3 r d^3 v + \int \nabla_v \cdot (f \boldsymbol{a}) d^3 r d^3 v \right] = 0$$

$$\frac{\partial}{\partial t} \left[\int f d^3 r d^3 v \right] + \left[\int \frac{\partial}{\partial r} \cdot (f \boldsymbol{v}) d^3 r d^3 v + \int \frac{\partial}{\partial v} \cdot (f \boldsymbol{a}) d^3 r d^3 v \right] = 0$$

Derivation of Boltzmann Equation (cont.)

• The phase space volume can be arbitrarily small, such that integrals are constant within the volume. Therefore we have

$$\frac{\partial f}{\partial t} + \frac{\partial}{\partial r} \cdot (f\boldsymbol{v}) + \frac{\partial}{\partial \boldsymbol{v}} \cdot (f\boldsymbol{a}) = 0$$

• But since *r* and *v* are independent variables, we can take *v* outside d/dr and similarly for *a*. Then we can write

$$\frac{\partial f}{\partial t} + \boldsymbol{v} \cdot \frac{\partial f}{\partial \boldsymbol{r}} + \boldsymbol{a} \cdot \frac{\partial f}{\partial \boldsymbol{v}} = 0$$

• Replacing a=F/m, we have

$$\frac{\partial f}{\partial t} + \boldsymbol{v} \cdot \frac{\partial f}{\partial \boldsymbol{r}} + \frac{\boldsymbol{F}}{m} \cdot \frac{\partial f}{\partial \boldsymbol{v}} = 0 \qquad (3.1)$$

• This is the *collisionless Boltzmann equation*. Can be used in hot plasma where collisions can be neglected

Vlasov equation

• Previous equation written in terms of generalized force. For plasmas, Lorentz force is of interest, so

$$\frac{\partial f}{\partial t} + \boldsymbol{v} \cdot \frac{\partial f}{\partial \boldsymbol{r}} + \frac{q}{m} [\boldsymbol{E} + (\boldsymbol{v} \times \boldsymbol{B})] \cdot \frac{\partial f}{\partial \boldsymbol{v}} = 0$$

• This is called the *Vlasov equation*. Can also be written as

$$\frac{\partial f}{\partial t} + \boldsymbol{v} \cdot \nabla f + \frac{q}{m} [\boldsymbol{E} + (\boldsymbol{v} \times \boldsymbol{B})] \cdot \frac{\partial f}{\partial \boldsymbol{v}} = 0 \quad (3.2)$$

- This is one of the most important and widely used equations in kinetic theory of plasmas.
- Maxwell's equations for *E* and *B* and the Vlasov equation represent a complete set of self-consistent equations.

Convective derivative in phase space

Distribution function f(r, v, t) depends on 7 independent variables.
 Total time derivative of f is:

$$\frac{df}{dt} = \frac{\partial f}{\partial t} + \frac{\partial f}{\partial x}\frac{\partial x}{\partial t} + \frac{\partial f}{\partial y}\frac{\partial y}{\partial t} + \frac{\partial f}{\partial z}\frac{\partial z}{\partial t} + \frac{\partial f}{\partial v_x}\frac{\partial z}{\partial t} + \frac{\partial f}{\partial v_y}\frac{\partial v_y}{\partial t} + \frac{\partial f}{\partial v_z}\frac{\partial v_z}{\partial t}$$
can be written as $\frac{df}{dt} = \frac{\partial f}{\partial t} + \mathbf{v} \cdot \frac{\partial f}{\partial \mathbf{r}} + \mathbf{a} \cdot \frac{\partial f}{\partial \mathbf{v}}$

• To appreciate meaning of this equation, consider f=f(r,t):

$$\frac{df}{dt} = \frac{\partial f}{\partial t} + \boldsymbol{v} \cdot \frac{\partial f}{\partial \boldsymbol{r}} \equiv \frac{Df}{Dt}$$

This

• Called the *convective derivative* or *Lagrangian derivative*. Second term gives change in *f* measured by an observed moving in the fluid frame.

Phase space evolution

• A plasma particle's state (r, v) evolves in phase space. In absence of collisions, points move along continuous curves and f obeys the continuity equation: $\frac{\partial f}{\partial t} + \nabla = \sqrt{[(\dot{r}, \dot{u})f]} = 0$

$$\frac{\partial f}{\partial t} + \nabla_{r,v} \cdot [(\dot{\boldsymbol{r}}, \dot{\boldsymbol{v}})f] = 0$$

- Called *Liouville equation*
- The Liouville equation describes the time evolution of the phase space distribution function. Liouvilles' theorem states that flows in phase space are incompressible.
- In Cartesian coordinates, equation reduces to

$$\frac{\partial f}{\partial t} + \frac{\partial}{\partial \boldsymbol{r}} \cdot (f\dot{\boldsymbol{r}}) + \frac{\partial}{\partial \boldsymbol{v}} \cdot (f\dot{\boldsymbol{v}}) = 0$$
$$\frac{\partial f}{\partial t} + \boldsymbol{v} \cdot \frac{\partial f}{\partial \boldsymbol{r}} + \boldsymbol{a} \cdot \frac{\partial f}{\partial \boldsymbol{v}} = 0$$

• Which is in form of the collisionless Boltzmann equation. The Bolzmann and Vlasov equations follow from Liouville equation.

Collisional Boltzmann and Vlasov equations

• In the presence of collisions, the Boltzmann equation can be written

$$\frac{\partial f}{\partial t} + \boldsymbol{v} \cdot \nabla f + \frac{\boldsymbol{F}}{m} \cdot \frac{\partial f}{\partial \boldsymbol{v}} = \left(\frac{\partial f}{\partial t}\right)_{coll}$$

where the term on the right is the time rate of change of *f* due to collisions. This is the *collisional Boltzmann equation*.

• Similarly, the Vlasov equation can be written

$$\frac{\partial f}{\partial t} + \boldsymbol{v} \cdot \nabla f + \frac{q}{m} [\boldsymbol{E} + (\boldsymbol{v} \times \boldsymbol{B})] \cdot \frac{\partial f}{\partial \boldsymbol{v}} = \left(\frac{\partial f}{\partial t}\right)_{coll}$$

- This is *the collisional Vlasov equation*. Describes change in particle distribution due to short-range interactions.
- When there are collisions with neutral atoms: $\left(\frac{\partial f}{\partial t}\right)_{coll} \approx \frac{f_n f}{\tau}$ where f_n is the neutral atom distribution function, and τ is the collision time. Called Krook collision model

Kinetic description of plasma

- Kinetic description of plasma is highly applicable treatment for collisionless plasma (wave-particle interaction, collisionless shock, particle acceleration)
- But evaluation of a 6D distribution function is difficult: analytical solutions of a kinetic equation are rare and numerical are expensive.
- Astrophysical application:
 - Dark matter evolution in cosmological simulation
 - Neutrino transport in core-collapse supernova simulation
 - Stellar interior (equation of state)
 - Collisionless shock (supernova blast wave)
 - Particle acceleration (astrophysical shock)

Moments of Bolzmann -Vlasov equation

- Under certain assumptions not necessary to obtain actual distribution function if only interested in the macroscopic values.
- Instead of solving Boltzmann or Vlasov equation for distribution function and integrating, can take integrals over *collisional Boltzmann-Vlasov equation* and solve for the quantities of interest.

$$\frac{\partial f}{\partial t} + \boldsymbol{v} \cdot \nabla f + \frac{q}{m} [\boldsymbol{E} + (\boldsymbol{v} \times \boldsymbol{B})] \cdot \frac{\partial f}{\partial \boldsymbol{v}} = \left(\frac{\partial f}{\partial t}\right)_{coll} \quad (3.3)$$

- Called taking the moments of Boltzmann-Vlasov equation
- Resulting equations known as the macroscopic transport equations, and form the foundation of plasma fluid theory.
- Results in derivation of the equations of magnetohydrodynamics (MHD).

Zeroth-order moment: continuity equation

• Lowest order moment obtained by integrating eq. (3.3):

$$\int \frac{\partial f}{\partial t} d\boldsymbol{v} + \int \boldsymbol{v} \cdot \nabla f d\boldsymbol{v} + \int \frac{q}{m} [\boldsymbol{E} + (\boldsymbol{v} \times \boldsymbol{B})] \cdot \frac{\partial f}{\partial \boldsymbol{v}} d\boldsymbol{v} = \int \left(\frac{\partial f}{\partial t}\right)_{coll} d\boldsymbol{v}$$

- The first-term gives: $\int \frac{\partial f}{\partial t} d\mathbf{v} = \frac{\partial}{\partial t} \int f d\mathbf{v} = \frac{\partial n}{\partial t}$ (3.4)
- Since *v* and *r* are independent, *v* is not effected by gradient operator:

$$\int \boldsymbol{v} \cdot \nabla f d\boldsymbol{v} = \nabla \cdot \int \boldsymbol{v} f d\boldsymbol{v}$$

• From previous one, the first order moment of distribution function is

$$oldsymbol{u} = rac{1}{n} \int oldsymbol{v} f(oldsymbol{r},oldsymbol{v},t) doldsymbol{v}$$

• Therefore,

$$\int \boldsymbol{v} \cdot \nabla f d\boldsymbol{v} = \nabla \cdot (n\boldsymbol{u}) \qquad (3.5)$$

Zeroth-order moment: continuity equation (cont.)

• For the third term, consider *E* and *B* separately. *E* term vanishes as

$$\int \boldsymbol{E} \cdot \frac{\partial f}{\partial \boldsymbol{v}} d\boldsymbol{v} = \int \frac{\partial}{\partial \boldsymbol{v}} \cdot (f\boldsymbol{E}) d\boldsymbol{v} = \int f\boldsymbol{E} \cdot d\boldsymbol{S} = 0 \quad (3.6a)$$

where using Gauss' divergence theorem in velocity space. The surface area of velocity space goes as v^2 . As $v \Rightarrow \infty$, $f \Rightarrow 0$ more quickly than $S \Rightarrow \infty$ (i.e., f typically goes as $1/v^2$. A Maxwellian goes as e^{-v^2}). Integral to v = infinity goes to zero.

Using vector identity, $\nabla \cdot (a\mathbf{A}) = \mathbf{A} \cdot \nabla a + a\nabla \cdot \mathbf{A}$. The $\mathbf{v} \ge \mathbf{B}$ term is

$$\int (\boldsymbol{v} \times \boldsymbol{B}) \cdot \frac{\partial f}{\partial \boldsymbol{v}} d\boldsymbol{v} = \int \frac{\partial}{\partial \boldsymbol{v}} \cdot (f\boldsymbol{v} \times \boldsymbol{B}) d\boldsymbol{v} - \int f \frac{\partial}{\partial \boldsymbol{v}} \cdot (\boldsymbol{v} \times \boldsymbol{B}) d\boldsymbol{v}$$
$$= \int f(\boldsymbol{v} \times \boldsymbol{B}) \cdot d\boldsymbol{S} - \int f \frac{\partial}{\partial \boldsymbol{v}} \cdot (\boldsymbol{v} \times \boldsymbol{B}) d\boldsymbol{v} = 0$$
(3.6b)

The first term on right again vanishes as *f* => 0 more quickly than S
 ⇒ ∞. The second term vanishes as *v* x *B* is perpendicular to *d/dv*

Zeroth-order moment: continuity equation (cont.2)

• Last-term is on right-hand side of eq. (3.3) :

$$\int \left(\frac{\partial f}{\partial t}\right)_{coll} d\boldsymbol{v} = \frac{\partial}{\partial t} \left[\int f d\boldsymbol{v}\right] = 0 \quad (3.7)$$

- This assumes that the total number of particles remains constant as collisions proceed.
- Combing eq. (3.4)-(3.7) yields the *equation of continuity*

$$\frac{\partial n}{\partial t} + \nabla \cdot (n\boldsymbol{u}) = 0 \qquad (3.8)$$

- First-term represents rate of change of particle concentration within a volume, second-term represents the divergence of particles of the flow of particles out of the volume.
- Eq (3.8) is the first of *the equations of magnetohydrodynamics* (MHD). Eq (3.8) is a continuity equation for mass or charge transport if we multiply *m* or *q*.

First-order of moment: momentum transport

• Re-write eq.(3.3) :

$$\frac{\partial f}{\partial t} + \boldsymbol{v} \cdot \nabla f + \frac{q}{m} [\boldsymbol{E} + (\boldsymbol{v} \times \boldsymbol{B})] \cdot \frac{\partial f}{\partial \boldsymbol{v}} = \left(\frac{\partial f}{\partial t}\right)_{coll}$$

 Next moment of the Boltzmann equation is obtained by multiplying Eq (3.3) by *mv* and integrating over *dv*.

$$m \int \boldsymbol{v} \frac{\partial f}{\partial t} d\boldsymbol{v} + m \int \boldsymbol{v}(\boldsymbol{v} \cdot \nabla) f d\boldsymbol{v} + q \int \boldsymbol{v} [\boldsymbol{E} + (\boldsymbol{v} \times \boldsymbol{B})] \cdot \frac{\partial f}{\partial \boldsymbol{v}} d\boldsymbol{v} = m \int \left(\frac{\partial f}{\partial t}\right)_{coll} d\boldsymbol{v}$$
(3.9)

- The right-hand side is the change of the momentum due to collisions and will be given the term P_{ij} .
- The first-term gives $m \int v \frac{\partial f}{\partial t} dv = m \frac{\partial}{\partial t} \int v f dv$ = $m \frac{\partial (nu)}{\partial t}$ (3.10)

First-order of moment: momentum transport (cont.)

• Next consider third-term:

$$\int \boldsymbol{v} [\boldsymbol{E} + (\boldsymbol{v} \times \boldsymbol{B})] \cdot \frac{\partial f}{\partial \boldsymbol{v}} dv = \int \frac{\partial}{\partial \boldsymbol{v}} \cdot [f \boldsymbol{v} (\boldsymbol{E} + \boldsymbol{v} \times \boldsymbol{B})] d\boldsymbol{v} - \int f \boldsymbol{v} \frac{\partial}{\partial \boldsymbol{v}} \cdot (\boldsymbol{E} + \boldsymbol{v} \times \boldsymbol{B}) d\boldsymbol{v} - \int f (\boldsymbol{E} + \boldsymbol{v} \times \boldsymbol{B}) \cdot \frac{\partial}{\partial \boldsymbol{v}} \boldsymbol{v} d\boldsymbol{v}$$

• The first and second to integrals on the right vanishes for same reasons as before. Therefore have,

$$q \int \boldsymbol{v} [\boldsymbol{E} + (\boldsymbol{v} \times \boldsymbol{B})] \cdot \frac{\partial f}{\partial \boldsymbol{v}} dv = -q \int f(\boldsymbol{E} + \boldsymbol{v} \times \boldsymbol{B}) d\boldsymbol{v}$$
$$= -qn(\boldsymbol{E} + \boldsymbol{u} \times \boldsymbol{B}) \quad (3.11)$$

• To evaluate second-term of eq.(3.9), use that \boldsymbol{v} does not depend on gradient operator: $\int \boldsymbol{v}(\boldsymbol{v} \cdot \nabla) f d\boldsymbol{v} = \int \nabla \cdot (f \boldsymbol{v} \boldsymbol{v}) d\boldsymbol{v}$ $= \nabla \cdot \int f \boldsymbol{v} \boldsymbol{v} d\boldsymbol{v}$

First-order of moment: momentum transport (cont.)

- Since the average of a quantity is 1/n times its weighted integral over v, we have
 ∇ · ∫ fvvdv = ∇ · (n⟨vv⟩)
- Now separate *v* into average fluid velocity *u* and a thermal velocity *w*:

$$v = u + w$$

• Since *u* is already averaged, so we have

$$\nabla \cdot (n \langle \boldsymbol{v} \boldsymbol{v} \rangle) = \nabla \cdot (n \boldsymbol{u} \boldsymbol{u}) + \nabla \cdot (n \langle \boldsymbol{w} \boldsymbol{w} \rangle) + 2\nabla \cdot (n \boldsymbol{u} \langle \boldsymbol{w} \rangle) \quad (3.12)$$

• The average thermal velocity is zero = > < w > = 0 and

$$\boldsymbol{P} = mn \langle \boldsymbol{w} \boldsymbol{w} \rangle \qquad (3.13)$$

is the stress tensor.

• P is a measure of the thermal motion in a fluid. If all particles moved with same steady velocity v, then w = 0 and thus P = 0 (i.e., a cold plasma).

First-order of moment: momentum transport (cont.3) Remaining term in Eq (3.9) can be written

$$\nabla \cdot (n\boldsymbol{u}\boldsymbol{u}) = \boldsymbol{u}\nabla \cdot (n\boldsymbol{u}) + n(\boldsymbol{u}\cdot\nabla)\boldsymbol{u} \quad (3.14)$$

• Correcting eq. (3.10), (3.11), (3.13), and (3.14), we have

$$m\frac{\partial}{\partial t}(n\boldsymbol{u}) + m\boldsymbol{u}\nabla\cdot(n\boldsymbol{u}) + mn(\boldsymbol{u}\cdot\nabla)\boldsymbol{u} + \nabla\cdot\boldsymbol{P} - qn(\boldsymbol{E}+\boldsymbol{u}\times\boldsymbol{B}) = \boldsymbol{P}_{ij}$$

• Combing first two terms (using cont. eq.), we obtain the *fluid equation of motion*:

$$mn\left[\frac{\partial \boldsymbol{u}}{\partial t} + (\boldsymbol{u}\cdot\nabla)\boldsymbol{u}\right] = qn(\boldsymbol{E} + \boldsymbol{u}\times\boldsymbol{B}) - \nabla\cdot\boldsymbol{P} + \boldsymbol{P}_{ij} \quad (3.15)$$

- This describes flow of momentum also called *momentum transport equation*.
- Eq (3.15) is a statement of conservation of momentum and represents force balance on components of plasma. On right are the Lorentz force, pressure, and collisions

Summary of moments of Vlasov equation

• Equations of MHD and multi-fluid theory are obtained by taking the moments of the Vlasov equation, corresponding to mass, momentum and energy.

 $\int (\text{Vlasov equation}) d\boldsymbol{v} \Rightarrow \text{conservation of mass}$ $\int (\text{Vlasov equation}) \boldsymbol{v} d\boldsymbol{v} \Rightarrow \text{conservation of momentum}$ $\int (\text{Vlasov equation}) \boldsymbol{v}^2 / 2 d\boldsymbol{v} \Rightarrow \text{conservation of energy}$

- Zeroth moment of the Vlasov equation results in the MHD mass continuity equation (eq. 3.8).
- First moment of the Vlasov equation gives the MHD momentum equation (eq. 3.15)
- Second moment of the Vlasov equation give the MHD energy transport equation